



7th International Conference on Computational and Mathematical
Biomedical Engineering, 27-29 June 2022, Milan, Italy

Soft Tissue Parameter Identification using Machine Learning

Sotirios Kakaletsis^{1*}, Emma Lejeune², Manuel K. Rausch^{1#}

¹Aerospace Engineering and Engineering Mechanics, The University of Texas at Austin

²Mechanical Engineering, Boston University

*kakalets@utexas.edu

#manuel.rausch@utexas.edu; www.manuelrausch.com

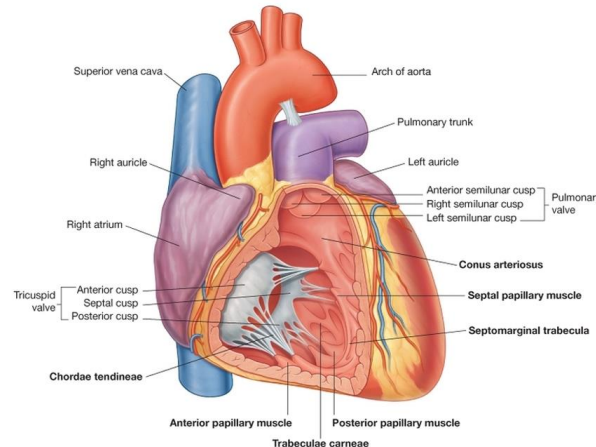


Motivation

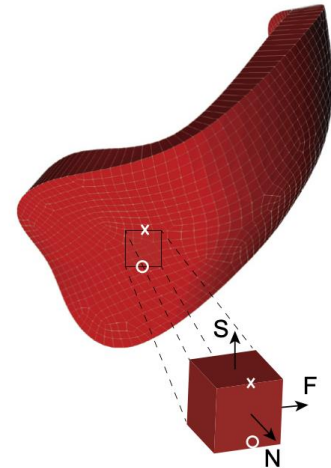
- Biomechanical characterization
 - Blood clot
 - Right ventricular myocardium



(Sugerman et al, 2020)

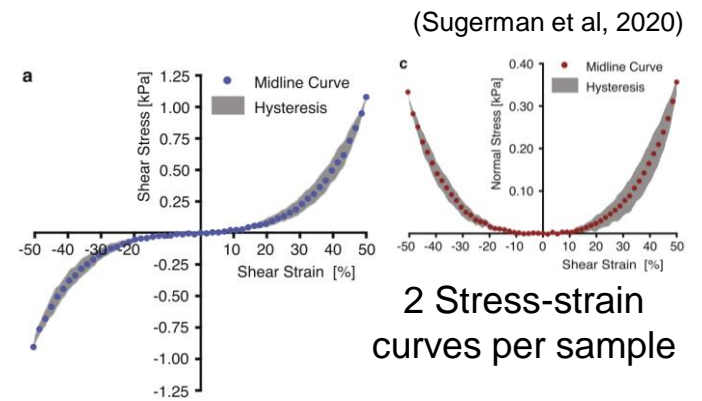
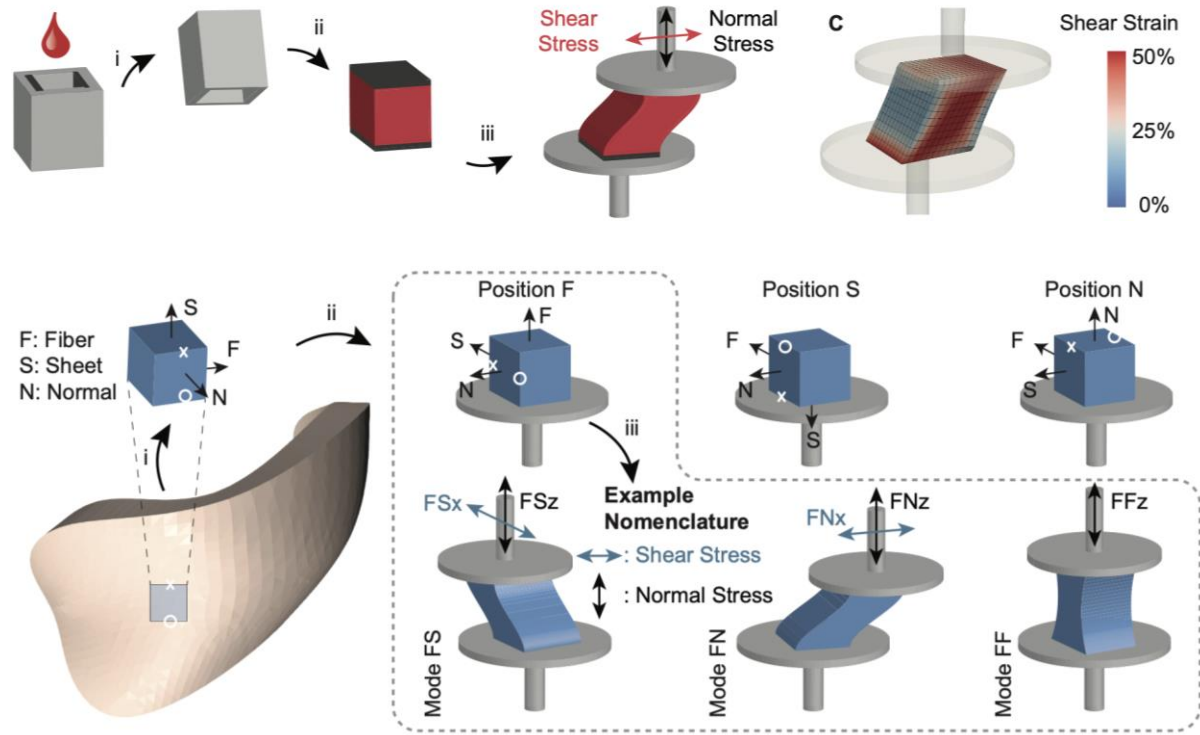


(Darke et al, 2009)

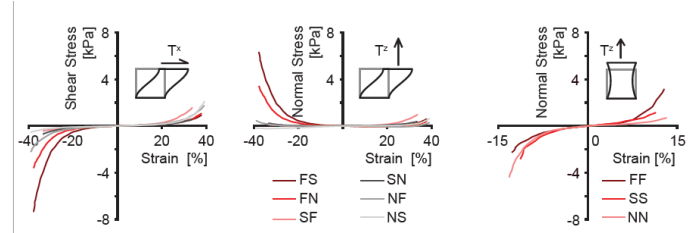


(Kakaletsis et al, 2021)

Experimental protocol



(Sugerman et al, 2020)
2 Stress-strain curves per sample



6 Simple shear modes

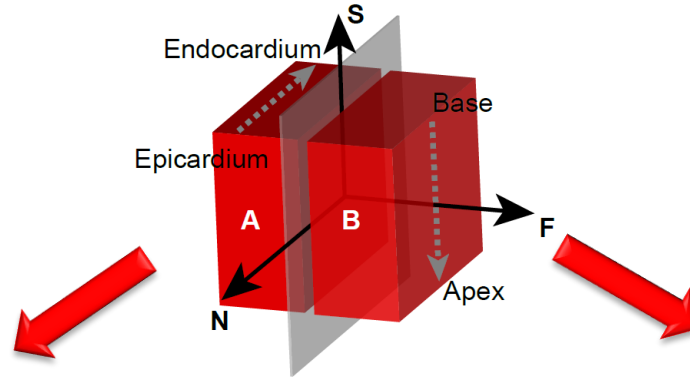
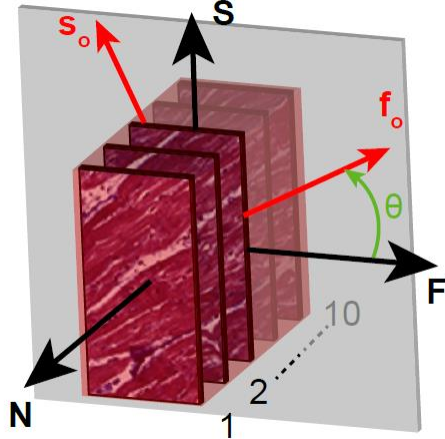
3 Uniaxial modes

15 Stress-strain curves per sample

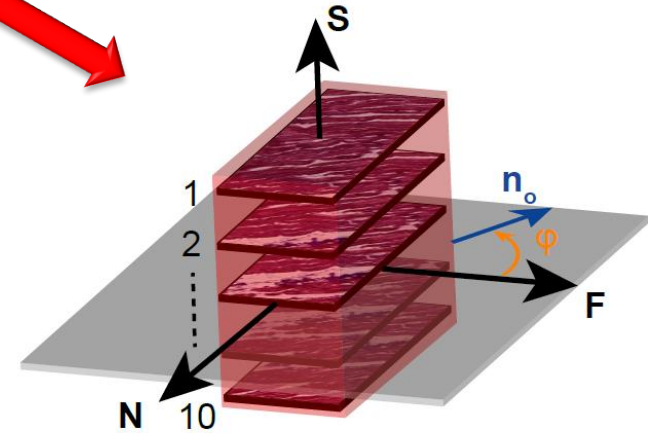


Histology

Epicardium to Endocardium Sections



Base to Apex Sections





Constitutive models

- Blood clot (hyperelastic, isotropic)

$$W = \frac{a}{b^2} (\lambda_1^b + \lambda_2^b + \lambda_3^b - 3) \quad (\text{Ogden, 1973})$$

- Myocardium (hyperelastic, anisotropic)

(Holzapfel et al, 2009)

Isotropic term
(amorphous matrix)

Fiber stiffness
contribution

Sheet stiffness
contribution

Shear coupling
(fiber-sheet interaction)

$$W = \frac{a}{2b} (\exp[b(I_1 - 3)] - 1) + \frac{a_f}{2b_f} (\exp[b_f(I_{4f} - 1)^2] - 1) + \frac{a_s}{2b_s} (\exp[b_s(I_{4s} - 1)^2] - 1) + \frac{a_{fs}}{2b_{fs}} (\exp[b_{fs}I_{8fs}^2] - 1)$$

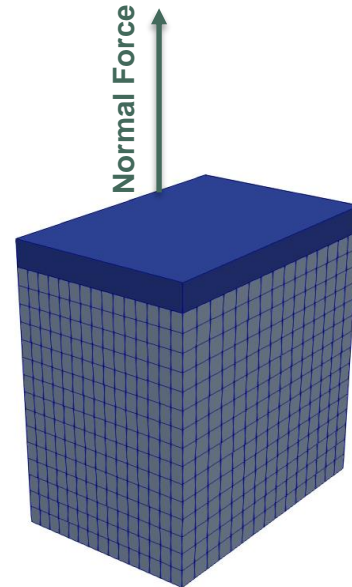
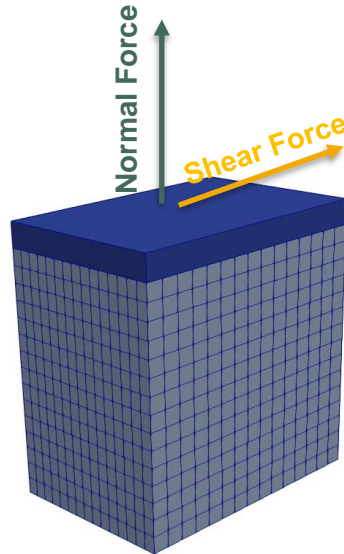
$$\int_0^{2\pi} H(I_{4f} - 1) \left\{ \frac{a_f}{2b_f} (\exp[b_f(I_{4f} - 1)^2] - 1) \right\} R(\theta) d\theta$$

In-plane fiber
dispersion



Objective

- Can we accelerate material parameter estimation using machine learning metamodels?

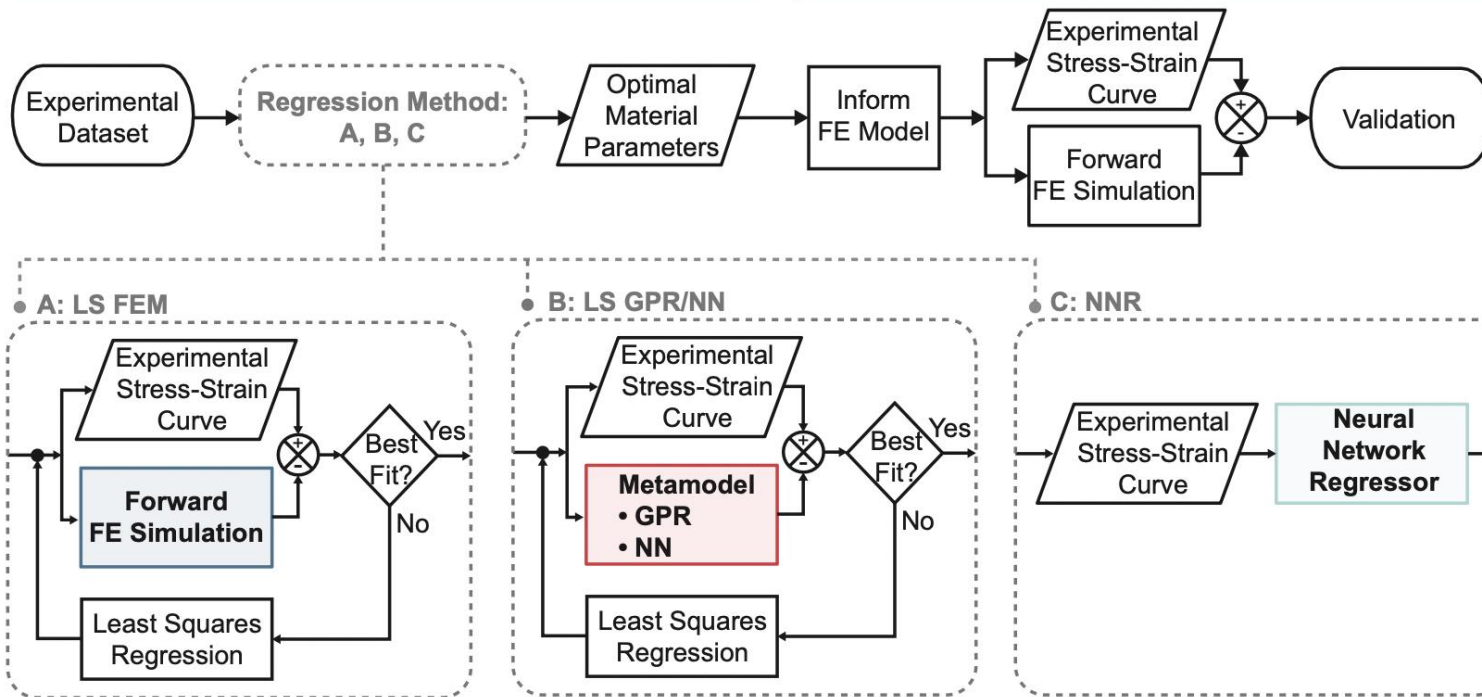




Pipeline

Parameter Identification

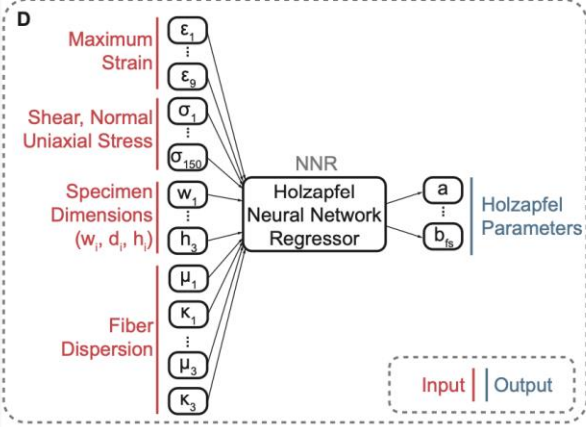
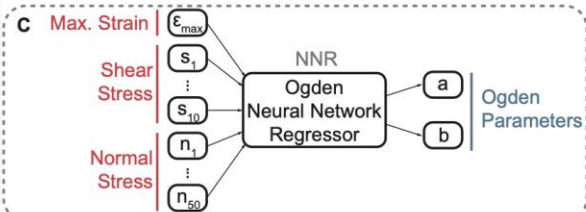
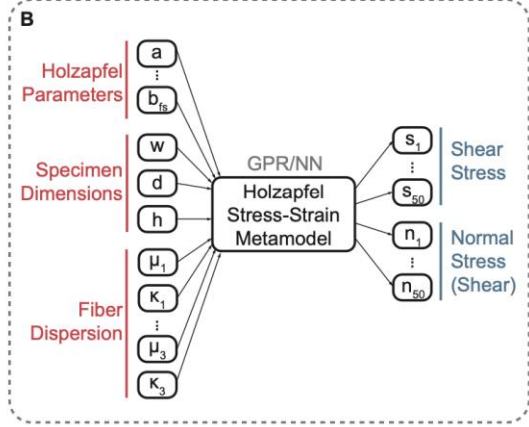
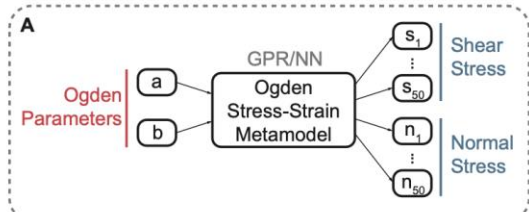
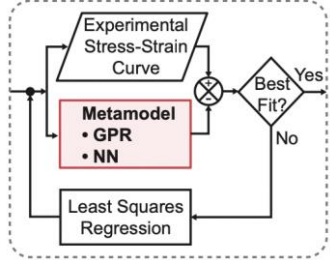
Validation



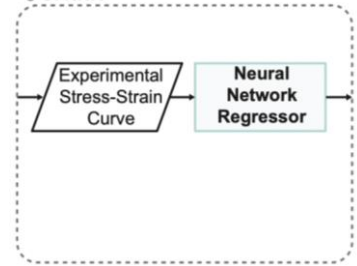


Machine Learning Approach

B: LS GPR/NN

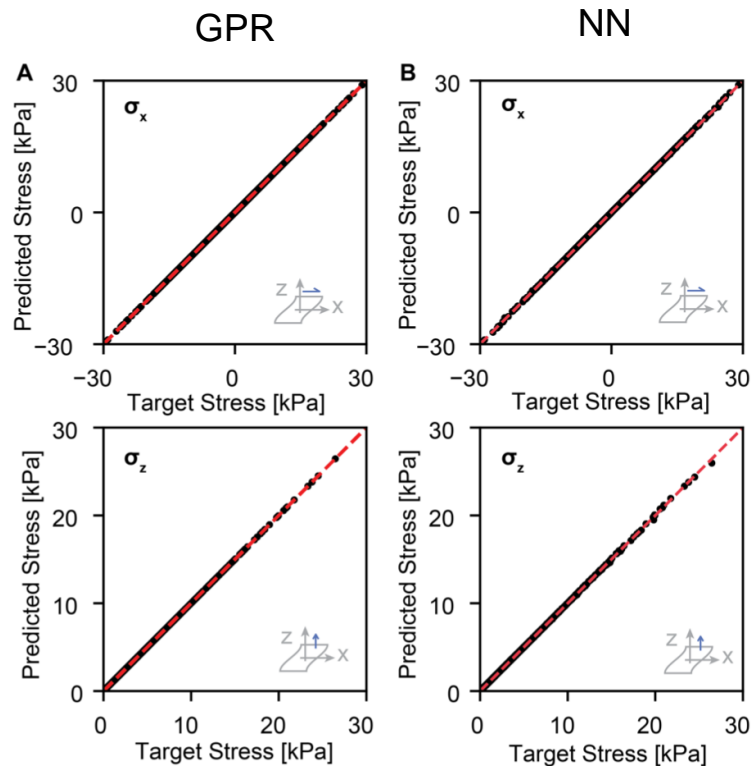


C: NNR





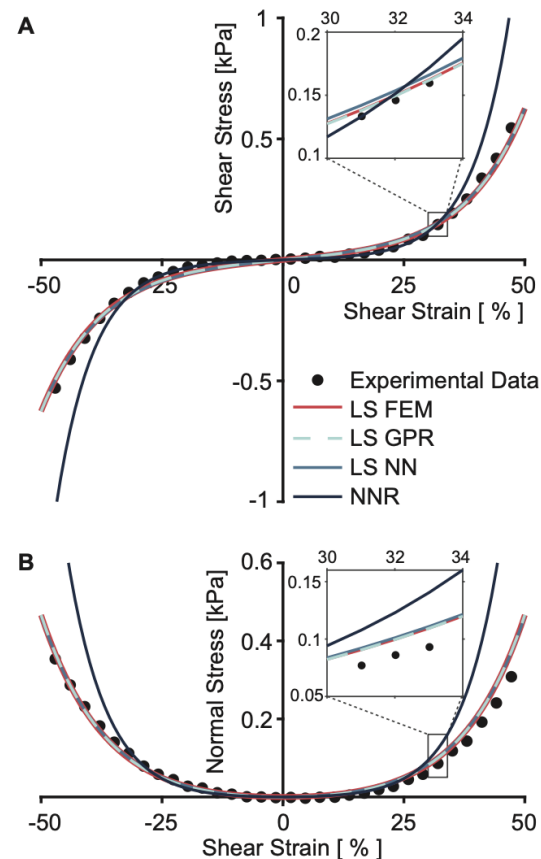
Training on Synthetic Data – Blood Clot





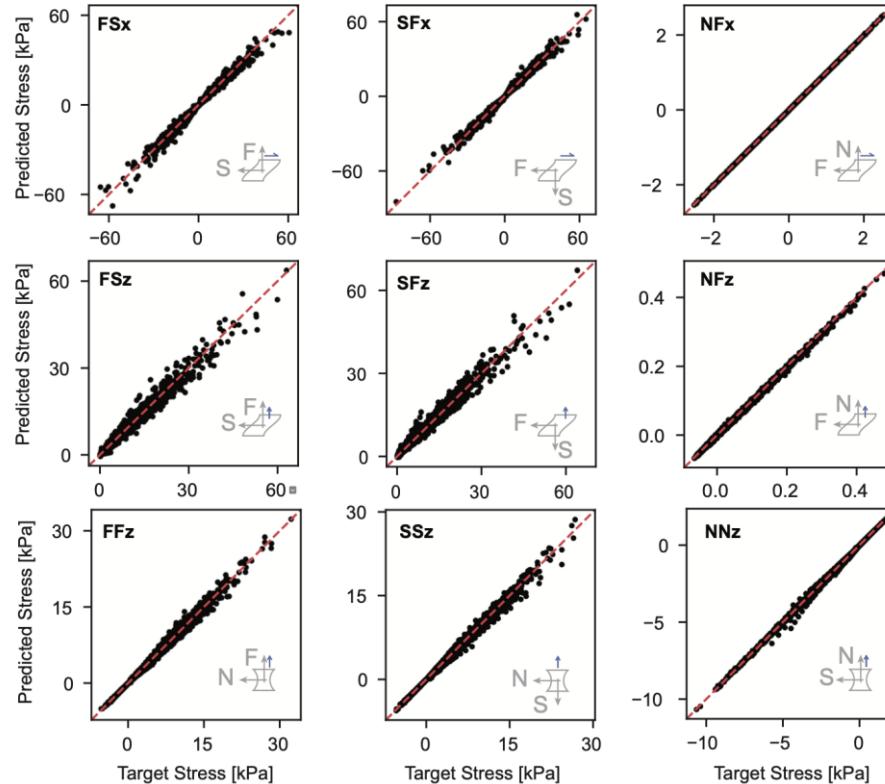
Validation-Blood Clot

Sample	Method	a	b	NMSE	Acc. Loss
		(Pa)	(-)		
Best	LS FEM	657.78	16.17	0.981	0.00
	LS GPR	627.25	16.49	0.980	0.01
	LS NN	656.99	16.24	0.980	0.01
	NNR	91.94	26.35	0.904	7.86
Median	LS FEM	530.39	16.32	0.989	0.00
	LS GPR	527.16	16.36	0.989	0.00
	LS NN	558.05	16.03	0.989	0.01
	NNR	194.67	26.21	-0.272	127.47
Worst	LS FEM	847.24	15.38	0.988	0.00
	LS GPR	845.42	15.39	0.988	0.00
	LS NN	881.57	15.14	0.988	0.01
	NNR	398.96	29.56	-23.212	2449.85





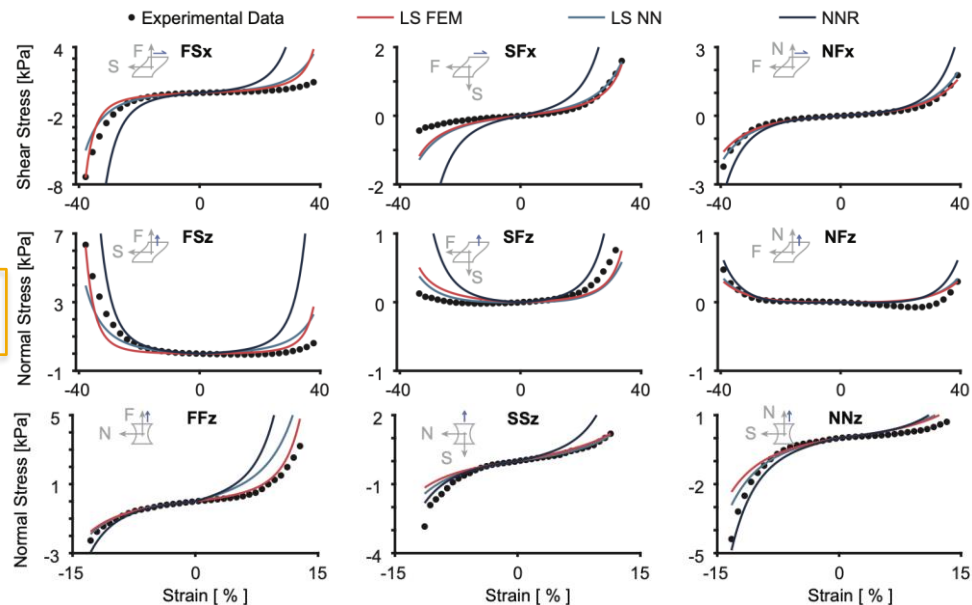
Training on Synthetic Data – Myocardium





Validation- Myocardium

Subject	Method	a (Pa)	b (-)	a_f (Pa)	b_f (-)	a_s (Pa)	b_s (-)	a_{fs} (Pa)	b_{fs} (-)	NMSE (-)	Acc. Los (%)
Best	LS FEM	1928.4	9.29	3925.4	19.42	1592.0	0.00	1587.8	0.00	0.878	0.0
	LS NN	2065.4	11.04	11580.1	8.72	780.1	0.03	0.1	18.59	0.758	13.7
	NNR	2319.3	18.88	3215.9	27.24	410.0	24.20	162.8	29.96	0.275	68.7
Median	LS FEM	1238.8	10.28	487.6	29.14	610.2	0.00	0.0	0.00	0.781	0.0
	LS NN	1259.7	11.50	2418.6	15.31	31.7	16.72	102.2	9.39	0.701	10.3
	NNR	1121.8	16.64	2787.2	27.06	794.0	20.96	1445.4	29.29	-8.349	1168.4
Worst	LS FEM	726.6	7.80	17707.5	0.00	0.2	0.12	0.0	0.00	0.713	0.0
	LS NN	765.8	10.89	15542.2	0.03	219.3	11.65	0.3	10.41	0.360	49.5
	NNR	1835.2	14.49	13346.3	27.00	7997.8	17.04	680.2	19.04	-Inf	Inf





Conclusions

- Can machine learning accelerate soft tissue parameter identification? –It depends.
 - Complexity of the corresponding experimental protocol
 - Feature space dimension
- Publicly available experimental and synthetic dataset
 - Future advances that further improve similar methods or follow entirely different approaches



References

- Kakaletsis S, Lejeune E, Rausch MK. Can machine learning accelerate soft material parameter identification from complex mechanical test data? (***Under Review***)
- Sugerman GP, Kakaletsis S, Thakkar P, Chokshi A, Parekh SH, Rausch MK. A whole blood clot thrombus mimic: Constitutive behavior under simple shear. *Journal of the Mechanical Behavior of Biomedical Materials*, 2021.
- Kakaletsis S, Meador WD, Mathur M, Sugerman GP, Jazwiec M, Lejeune E, Timek TA, Rausch MK. Right ventricular myocardial mechanics: Multi-modal deformation, microstructure, and modeling. *Acta Biomaterialia*, 2021.



Thank you!

- Dr. Manuel Rausch, UT Austin (www.manuelrausch.com)
- Dr. Emma Lejeune, Boston University
- Soft Tissue Biomechanics Lab, UT Austin

- Funding sources



American
Heart
Association®



The University of Texas at Austin
Aerospace Engineering
and Engineering Mechanics
Cockrell School of Engineering

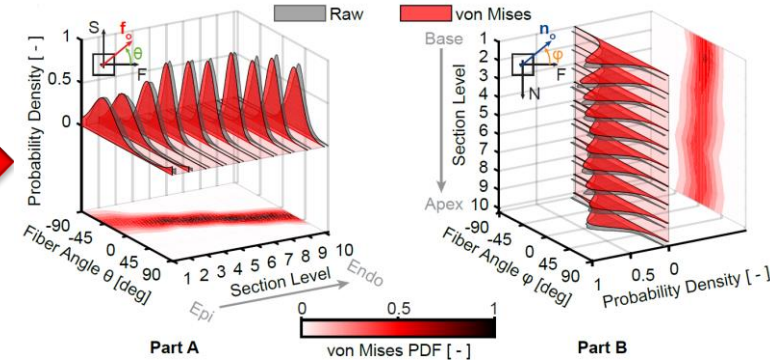
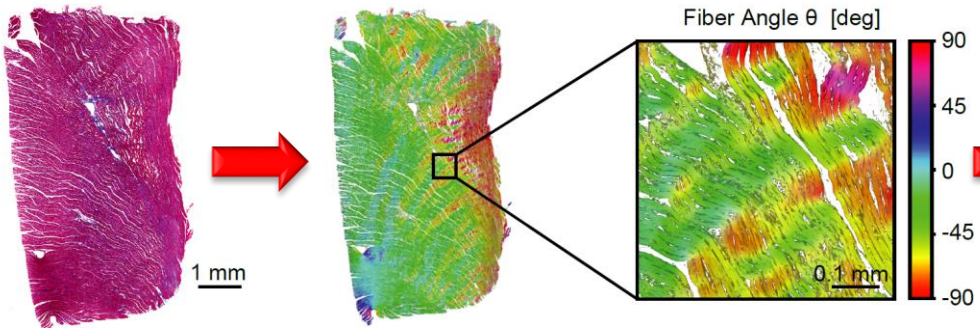


The University of Texas at Austin

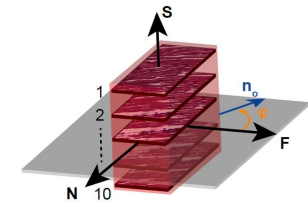
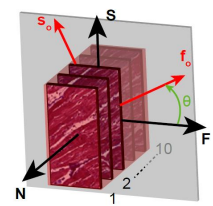
Cockrell School of Engineering



Fiber Orientation



- High resolution images of histology slides
- Directional image analysis (ImageJ / OrientationJ)
- π -periodic von Mises distributions of fiber orientation angles through section levels





Holzappel-Ogden Model

Right ventricular myocardium exhibited:

- Nonlinear response
- Anisotropic behavior
- Heterogeneous properties.

Structurally based constitutive model by Holzappel & Ogden (2009):

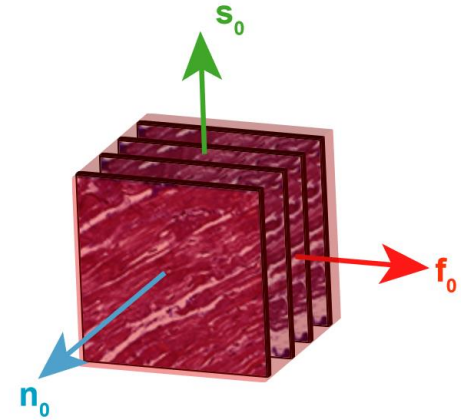
$$W = \frac{a}{2b} (\exp[b(I_1 - 3)] - 1) + \frac{a_f}{2b_f} (\exp[b_f(I_{4f} - 1)^2] - 1) + \frac{a_s}{2b_s} (\exp[b_s(I_{4s} - 1)^2] - 1) + \frac{a_{fs}}{2b_{fs}} (\exp[b_{fs}I_{8fs}^2] - 1)$$

Isotropic term
(amorphous matrix)

Fiber stiffness
contribution

Sheet stiffness
contribution

Shear coupling
(fiber-sheet interaction)



Where the anisotropic **invariants** of the deformation tensor are given by:

$$I_{4f} = \mathbf{f}_0 \cdot (\mathbf{C}\mathbf{f}_0)$$

$$I_{4s} = \mathbf{s}_0 \cdot (\mathbf{C}\mathbf{s}_0)$$

$$I_{8fs} = \mathbf{f}_0 \cdot (\mathbf{C}\mathbf{s}_0)$$

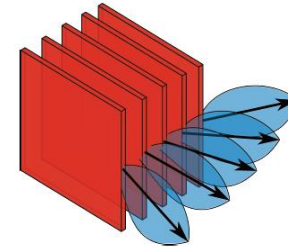


Include fiber dispersion

Modify strain energy to account for in-plane fiber dispersion:

$$W = \frac{a}{2b} (\exp[b(I_1 - 3)] - 1) + \frac{a_f}{2b_f} (\exp[b_f(I_{4f} - 1)^2] - 1) + \frac{a_s}{2b_s} (\exp[b_s(I_{4s} - 1)^2] - 1) + \frac{a_{fs}}{2b_{fs}} (\exp[b_{fs}I_{8fs}^2] - 1)$$

$$\int_0^{2\pi} H(I_{4f} - 1) \left\{ \frac{a_f}{2b_f} (\exp[b_f(I_{4f} - 1)^2] - 1) \right\} R(\theta) d\theta$$



where

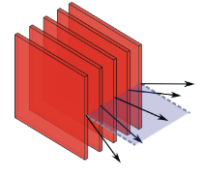
- $H(I_{4f} - 1)$ the Heaviside step function to ensure fibers contribute **only under tension**
- $R(\theta)$ is π -periodic von Mises function with $R(\theta) = \frac{\exp(b \cos(2[\theta - \mu]))}{2\pi I_0(b)}$
- Angular integration approach



Model Classes

Model Class 1

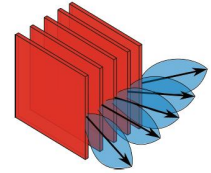
No dispersion



$$\frac{a_f}{2b_f} (\exp [b_f (I_{4f} - 1)^2] - 1)$$

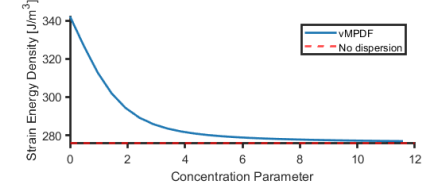
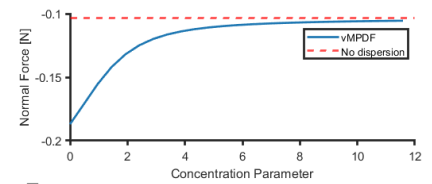
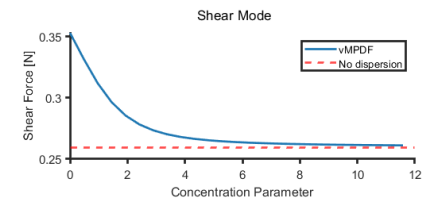
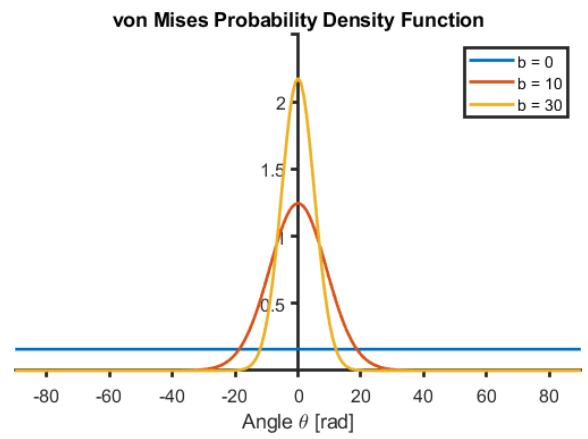
Model Class 2

2D von Mises Distribution



$$\int_0^{2\pi} H(I_{4f} - 1) \left\{ \frac{a_f}{2b_f} (\exp [b_f (I_{4f} - 1)^2] - 1) \right\} R(\theta) d\theta$$

For highly concentrated fiber distributions (high concentration parameter b) the two classes are equivalent:





Incompressibility

- Decompose deformation gradient into volumetric and isochoric part:

$$\mathbf{F} = (J^{1/3} \mathbf{I}) \cdot (J^{-1/3} \mathbf{F}) = \mathbf{F}_{vol} \cdot \tilde{\mathbf{F}}$$

Note: $\det(\mathbf{F}_{vol}) = J$ and $\det(\tilde{\mathbf{F}}) = 1$

- Volumetric-Isochoric split of strain energy function

$$W(\mathbf{C}) = U(J) + W_{iso}(\tilde{\mathbf{C}})$$

where $U(J) = K/2 \ln(J)^2$, $\tilde{\mathbf{C}} = \tilde{\mathbf{F}}^T \tilde{\mathbf{F}}$ and W_{iso} as presented previously, by substituting the isochoric invariants

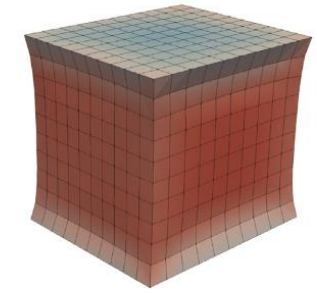
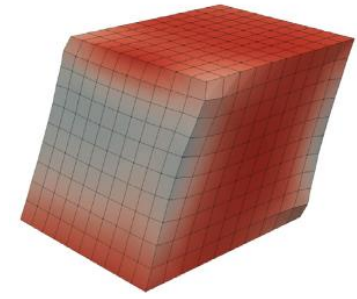
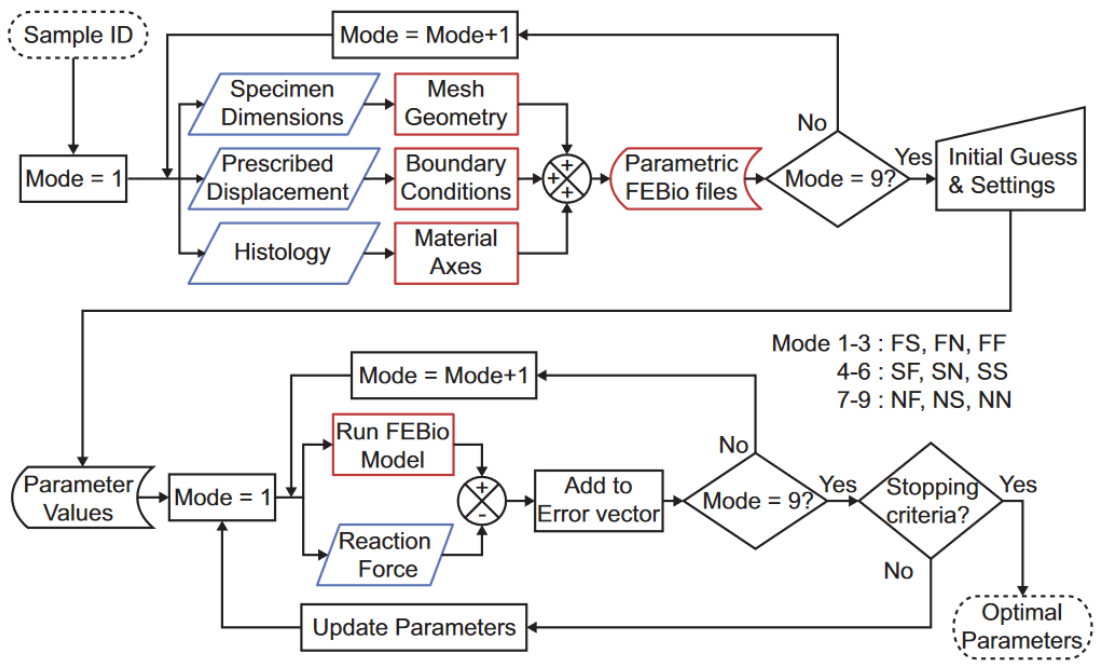
$$I_{4f} = \mathbf{f}_0 \cdot (\tilde{\mathbf{C}} \mathbf{f}_0)$$

$$I_{4s} = \mathbf{s}_0 \cdot (\tilde{\mathbf{C}} \mathbf{s}_0)$$

$$I_{8fs} = \mathbf{f}_0 \cdot (\tilde{\mathbf{C}} \mathbf{s}_0)$$

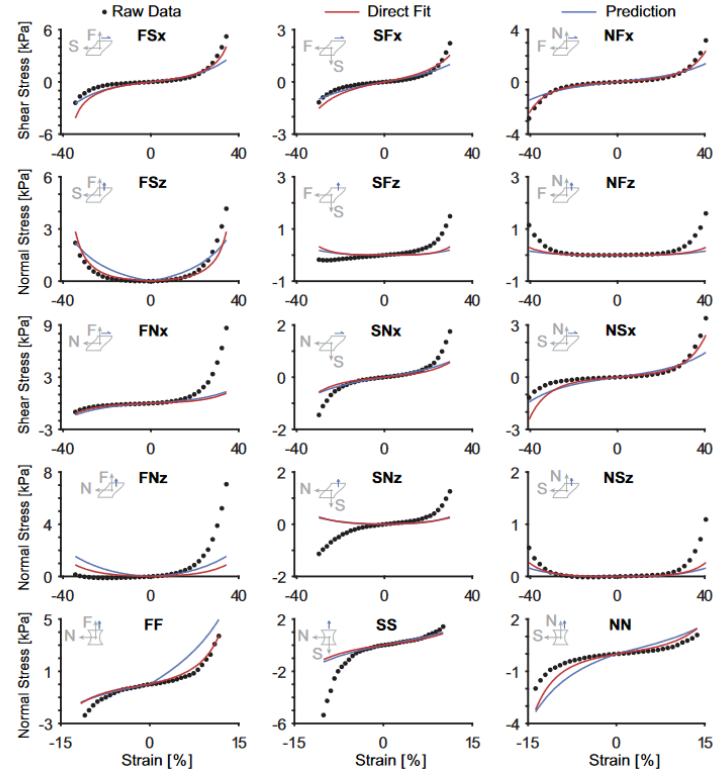
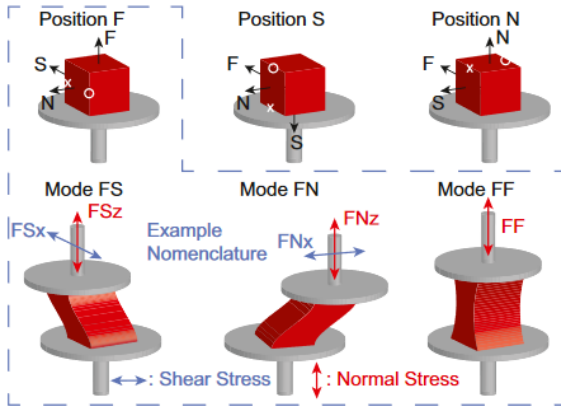


Material Parameter Estimation





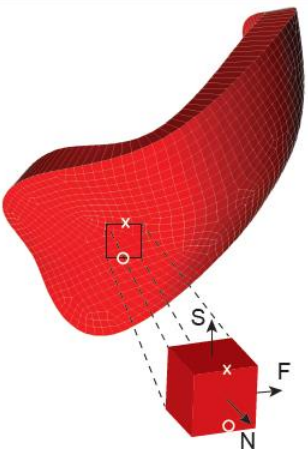
Material Parameter Estimation



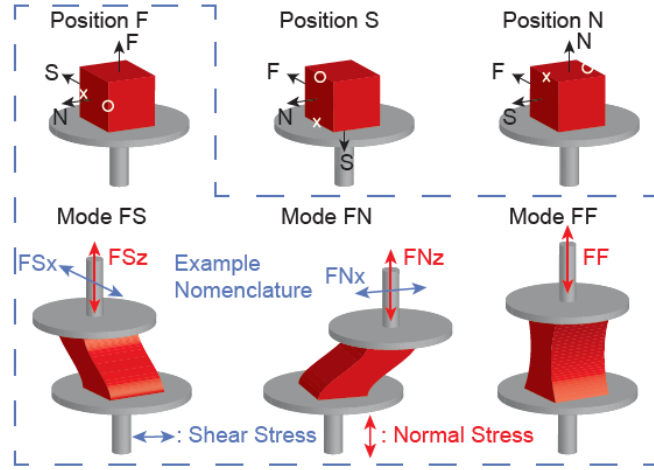


Mechanical Testing

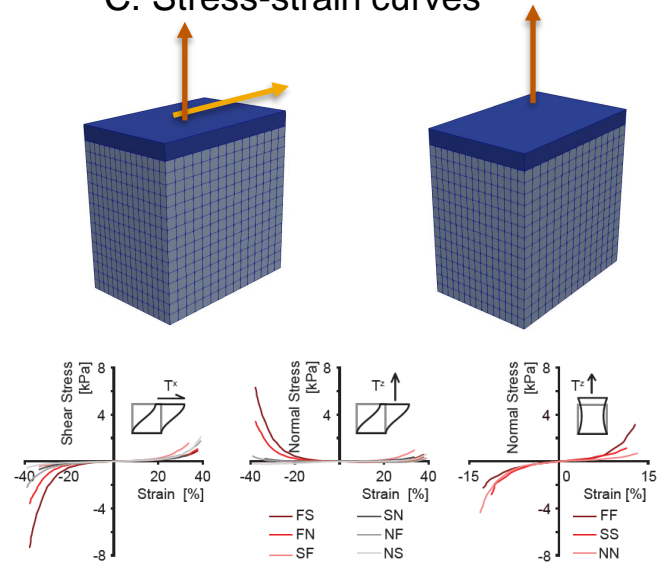
A. Excise specimens
 (10x10x10mm cubes)



B. Test in 9 different modes

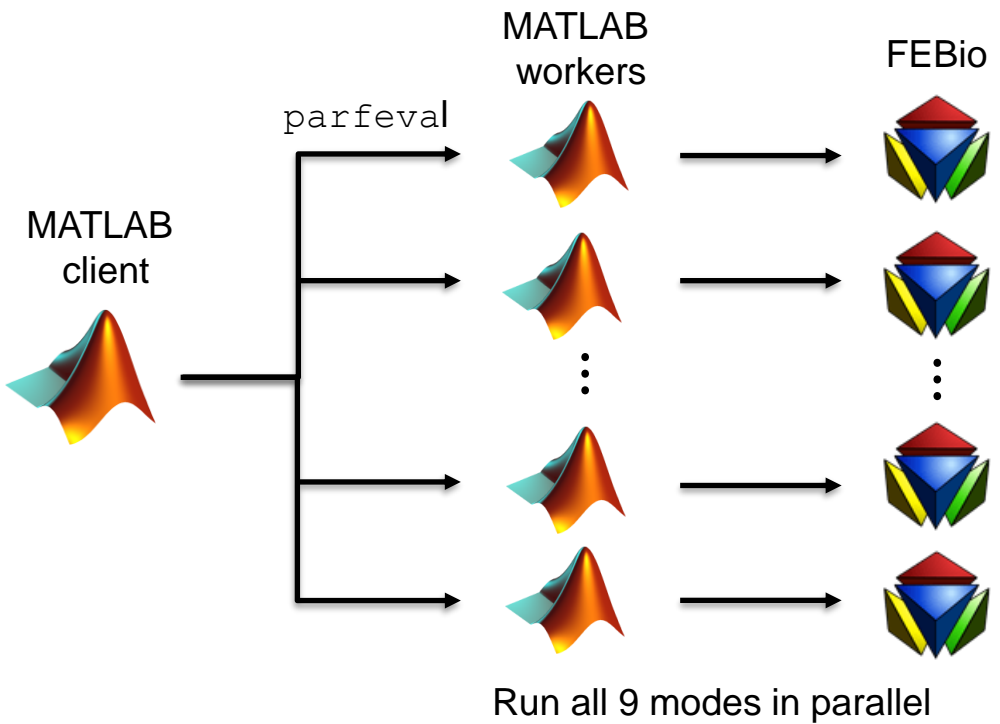


C. Stress-strain curves





Practical Aspects



	Element Type	Run Time 9 modes [sec]	Run Time 9 modes [min]	Run time for 15 iterations [h]
Class 1	Linear	23.2	0.4	0.9
	Quad	167.8	2.8	6.3
Class 2	Linear	70.3	1.2	2.6
	Quad	184.7	3.1	7.0

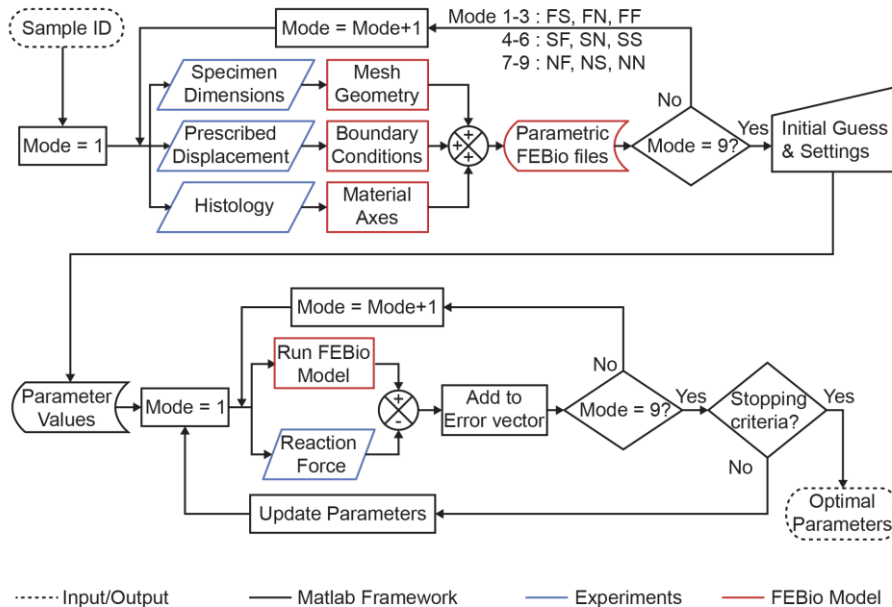
9 modes * 9 param var. = **81 FEBio runs / iteration**

15 iter. * 81 = **1,215 FEBio runs for converged parameters**

Expensive!



Machine Learning Approach



Substitute forward FE simulations by a ML metamodel. Motivation:

- A gradient-based inverse method using FE simulations is very expensive!
- Even more expensive for continuous fiber distribution materials using the angular integration method.
- Predictive power: replace the entire pipeline to estimate material parameters.



The problem

Input

Target

8 Material
Parameters

- a
- b
- a_f
- b_f
- a_s
- b_s
- a_{fs}
- b_{fs}

2 Fiber
Angles

- φ
- θ

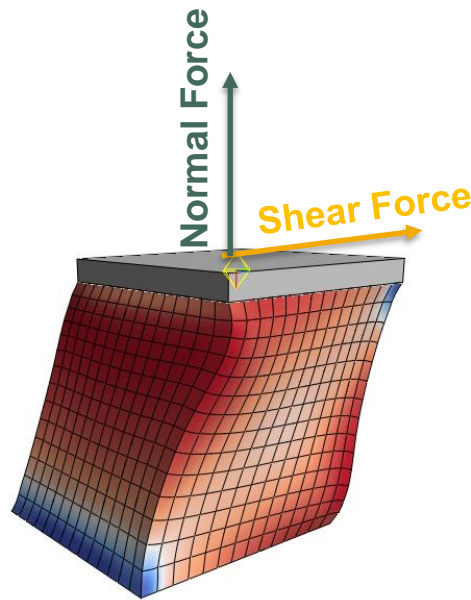
**Meta-
model**

- $F_x @ -40\%$
- $F_x @ -38\%$
- \vdots
- $F_x @ +40\%$

- $F_z @ -40\%$
- $F_z @ -38\%$
- \vdots
- $F_z @ +40\%$

Shear force
at 50 strain values

Normal force
at 50 strain values



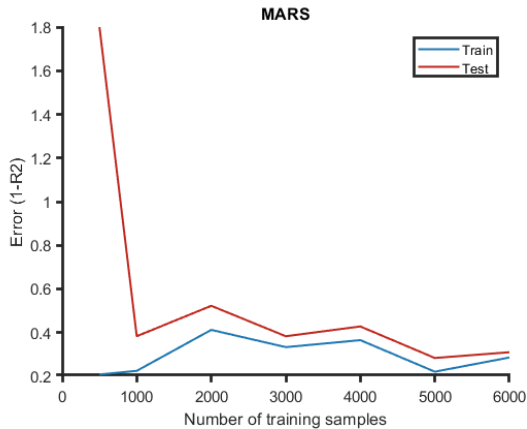
10,000 Samples

100 values / sample

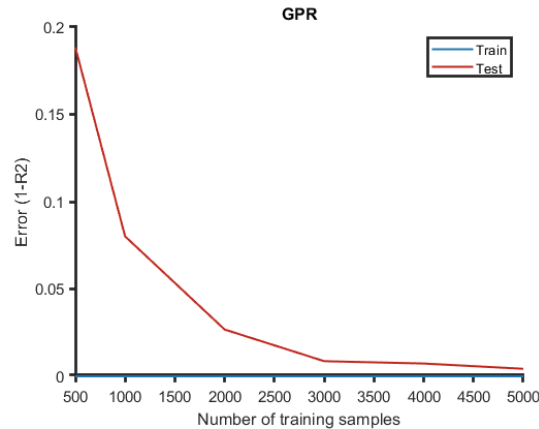


Metamodel Selection

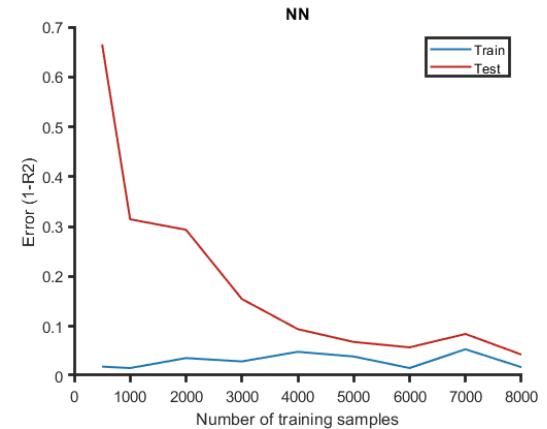
Multivariate Adaptive Regression Splines



Gaussian Process Regressor Anisotropic RBF kernel

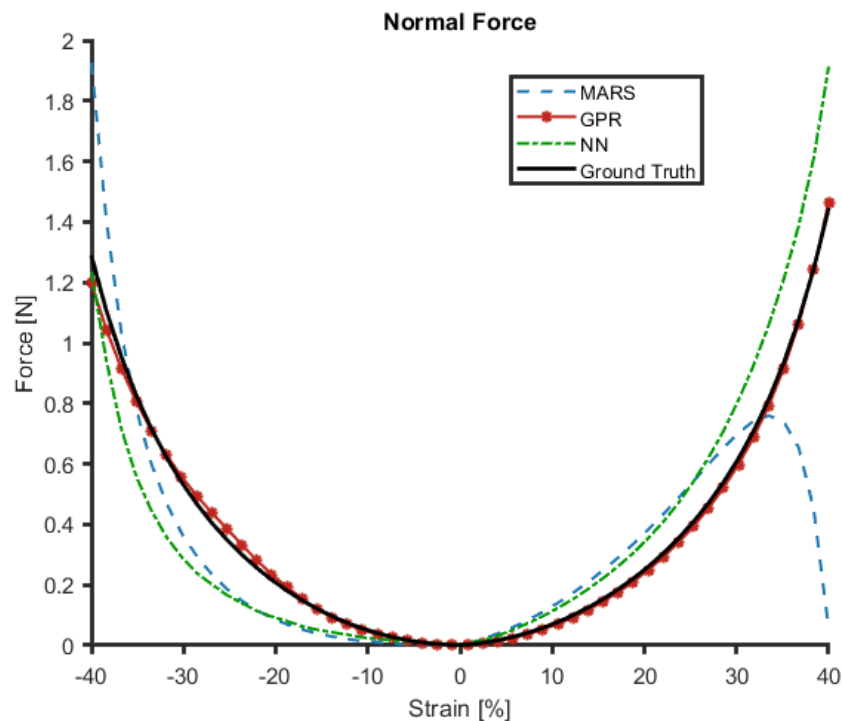
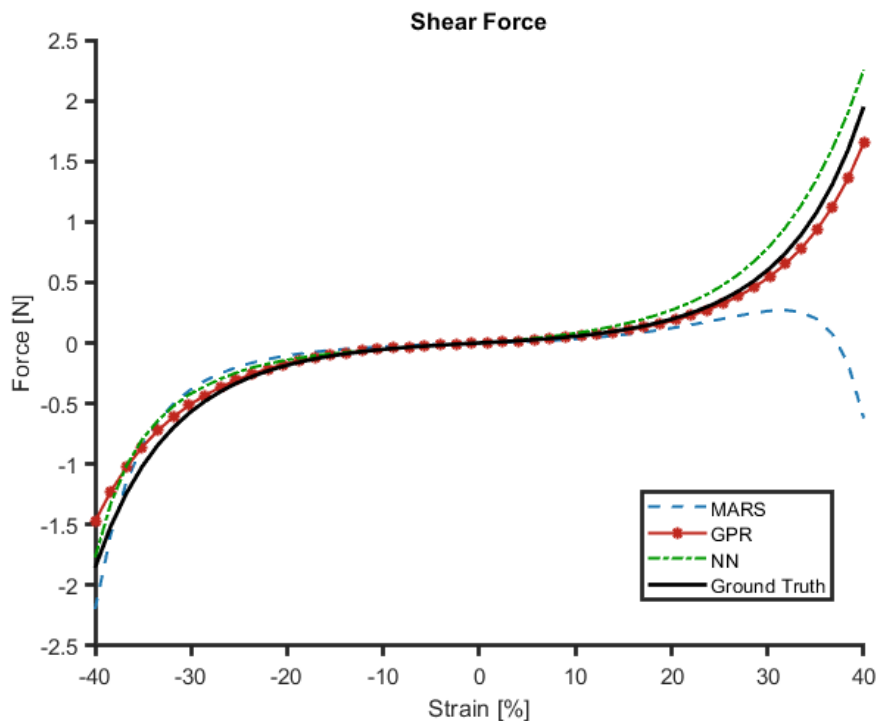


Neural Network Multi-layer Perceptron Regressor





Preliminary Results



Stress-strain prediction of one sample in validation set, trained with 5,000 samples



The University of Texas at Austin

Cockrell School of Engineering